

(12) PATENT APPLICATION PUBLICATION

(21) Application No.202511062763 A

(19) INDIA

(22) Date of filing of Application :01/07/2025

(43) Publication Date : 15/08/2025

(54) Title of the invention : AN AUTONOMOUS FIRE-EXTINGUISHING NANOBOT SYSTEM FOR RAPID FIRE DETECTION AND SUPPRESSION

(51) International classification :G01J0005000000, G08B0017120000, G01J0005020000, G01J0005060000, G01J0005040000

(86) International Application No :NA  
Filing Date :NA

(87) International Publication No : NA

(61) Patent of Addition to Application Number :NA  
Filing Date :NA

(62) Divisional to Application Number :NA  
Filing Date :NA

(71)Name of Applicant :  
**1)NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY**  
 Address of Applicant :19, KNOWLEDGE PARK-II, INSTITUTIONAL AREA, GREATER NOIDA-201306, GAUTAM BUDDHA NAGAR, UTTAR PRADESH, INDIA Gautam Buddha Nagar -----  
**Name of Applicant : NA**  
**Address of Applicant : NA**  
 (72)Name of Inventor :  
**1)DR. CHANDAN CHOUBEY**  
 Address of Applicant :NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, 19, KNOWLEDGE PARK-II, INSTITUTIONAL AREA, GREATER NOIDA-201306, GAUTAM BUDDHA NAGAR, UTTAR PRADESH, INDIA Gautam Buddha Nagar -----  
**2)RAHUL KUMAR SHARMA**  
 Address of Applicant :NOIDA INSTITUTE OF ENGINEERING & TECHNOLOGY, 19, KNOWLEDGE PARK-II, INSTITUTIONAL AREA, GREATER NOIDA-201306, GAUTAM BUDDHA NAGAR, UTTAR PRADESH, INDIA Gautam Buddha Nagar -----

(57) Abstract :  
 Disclosed herein is an autonomous fire-extinguishing nanobot system for rapid fire detection and suppression (100) comprises a nanobot body (102) structurally designed to navigate through confined and hazardous environments. The system also includes a thermal sensor module (104) configured to detect thermal radiation or temperature variations. The system also includes a flame detection unit (106) operable to identify fire occurrences. The system also includes a Wi-Fi communication module (108) configured to establish wireless communication with Android mobile devices. The system also includes a heat-intensity-based positioning sensor unit (110), calculates the most immediate and effective path toward the origin of fire. The system also includes a pumping unit (112) incorporating a microfluidic water-spray mechanism. The system also includes a servo motor unit (114) having low-RPM and high-torque capability enabling autonomous stair climbing and movement through uneven or obstructed paths.

No. of Pages : 30 No. of Claims : 10